

---

# DeePMD-kit

Deep Potential

Aug 20, 2021



# USER GUIDE

<b>1</b>	<b>Installation</b>	<b>3</b>
1.1	Easy installation methods . . . . .	3
1.2	Install from source code . . . . .	4
1.3	Install i-PI . . . . .	8
1.4	Building conda packages . . . . .	9
<b>2</b>	<b>Getting Started</b>	<b>11</b>
2.1	Prepare data . . . . .	11
2.2	Train a model . . . . .	13
2.3	Freeze a model . . . . .	16
2.4	Test a model . . . . .	16
2.5	Compress a model . . . . .	18
2.6	Model inference . . . . .	20
2.7	Run MD . . . . .	21
2.8	Known limitations . . . . .	23
<b>3</b>	<b>TensorBoard Usage</b>	<b>25</b>
3.1	Highlighted features . . . . .	25
3.2	How to use Tensorboard with DeePMD-kit . . . . .	25
3.3	Examples . . . . .	26
3.4	Attention . . . . .	30
<b>4</b>	<b>FAQs</b>	<b>31</b>
4.1	Trouble shooting . . . . .	31
4.2	Parameters setting . . . . .	31
<b>5</b>	<b>Data</b>	<b>33</b>
5.1	Definition . . . . .	33
5.2	Data conversion . . . . .	33
<b>6</b>	<b>Training Parameters</b>	<b>35</b>
<b>7</b>	<b>Developer Guide</b>	<b>57</b>
<b>8</b>	<b>License</b>	<b>59</b>
<b>9</b>	<b>Authors and Credits</b>	<b>61</b>
9.1	Package Contributors . . . . .	61
9.2	Other Credits . . . . .	62



DeePMD-kit is a package written in Python/C++, designed to minimize the effort required to build deep learning based model of interatomic potential energy and force field and to perform molecular dynamics (MD). This brings new hopes to addressing the accuracy-versus-efficiency dilemma in molecular simulations. Applications of DeePMD-kit span from finite molecules to extended systems and from metallic systems to chemically bonded systems.

---

**Important:** The project DeePMD-kit is licensed under [GNU LGPLv3.0](#). If you use this code in any future publications, please cite this using *Han Wang, Linfeng Zhang, Jiequn Han, and Weinan E. "DeePMD-kit: A deep learning package for many-body potential energy representation and molecular dynamics." Computer Physics Communications 228 (2018): 178-184.*

---



## INSTALLATION

- *Easy installation methods*
- *Install from source code*
- *Install i-PI*
- *Building conda packages*

### 1.1 Easy installation methods

There various easy methods to install DeePMD-kit. Choose one that you prefer. If you want to build by yourself, jump to the next two sections.

After your easy installation, DeePMD-kit (`dp`) and LAMMPS (`lmp`) will be available to execute. You can try `dp -h` and `lmp -h` to see the help. `mpirun` is also available considering you may want to run LAMMPS in parallel.

- *Install off-line packages*
- *Install with conda*
- *Install with docker*

#### 1.1.1 Install off-line packages

Both CPU and GPU version offline packages are available in [the Releases page](#).

Some packages are split into two files due to size limit of GitHub. One may merge them into one after downloading:

```
cat deepmd-kit-2.0.0-cuda11.1_gpu-Linux-x86_64.sh.0 deepmd-kit-2.0.0-cuda11.1_gpu-Linux-  
↪x86_64.sh.1 > deepmd-kit-2.0.0-cuda11.1_gpu-Linux-x86_64.sh
```

#### 1.1.2 Install with conda

DeePMD-kit is available with [conda](#). Install [Anaconda](#) or [Miniconda](#) first.

One may create an environment that contains the CPU version of DeePMD-kit and LAMMPS:

```
conda create -n deepmd deepmd-kit=*cpu lammmps-dp=*cpu -c https://conda.deepmodeling.  
↪org
```

Or one may want to create a GPU environment containing [CUDA Toolkit](#):

```
conda create -n deepmd deepmd-kit=*=*gpu lammps-dp=*=*gpu cudatoolkit=11.1 -c https://  
↳conda.deepmodeling.org -c nvidia
```

One could change the CUDA Toolkit version from 11.1 to 10.1 or 10.0.

One may specify the DeePMD-kit version such as 2.0.0 using

```
conda create -n deepmd deepmd-kit=2.0.0=*cpu lammps-dp=2.0.0=*cpu -c https://conda.  
↳deepmodeling.org
```

One may enable the environment using

```
conda activate deepmd
```

### 1.1.3 Install with docker

A docker for installing the DeePMD-kit is available [here](#).

To pull the CPU version:

```
docker pull ghcr.io/deepmodeling/deepmd-kit:2.0.0_cpu
```

To pull the GPU version:

```
docker pull ghcr.io/deepmodeling/deepmd-kit:2.0.0_cuda10.1_gpu
```

## 1.2 Install from source code

Please follow our [github](#) webpage to download the [latest released version](#) and [development version](#).

Or get the DeePMD-kit source code by `git clone`

```
cd /some/workspace  
git clone --recursive https://github.com/deepmodeling/deepmd-kit deepmd-kit
```

The `--recursive` option clones all [submodules](#) needed by DeePMD-kit.

For convenience, you may want to record the location of source to a variable, saying `deepmd_source_dir` by

```
cd deepmd-kit  
deepmd_source_dir=`pwd`
```

- *Install the python interaction*
  - *Install the Tensorflow's python interface*
  - *Install the DeePMD-kit's python interface*
- *Install the C++ interface*
  - *Install the Tensorflow's C++ interface*
  - *Install the DeePMD-kit's C++ interface*
- *Install LAMMPS's DeePMD-kit module*



## 1.2.1 Install the python interface

### Install the Tensorflow's python interface

First, check the python version on your machine

```
python --version
```

We follow the virtual environment approach to install the tensorflow's Python interface. The full instruction can be found on [the tensorflow's official website](#). Now we assume that the Python interface will be installed to virtual environment directory \$tensorflow\_venv

```
virtualenv -p python3 $tensorflow_venv
source $tensorflow_venv/bin/activate
pip install --upgrade pip
pip install --upgrade tensorflow==2.3.0
```

It is notice that everytime a new shell is started and one wants to use DeePMD-kit, the virtual environment should be activated by

```
source $tensorflow_venv/bin/activate
```

if one wants to skip out of the virtual environment, he/she can do

```
deactivate
```

If one has multiple python interpreters named like python3.x, it can be specified by, for example

```
virtualenv -p python3.7 $tensorflow_venv
```

If one does not need the GPU support of deepmd-kit and is concerned about package size, the CPU-only version of tensorflow should be installed by

```
pip install --upgrade tensorflow-cpu==2.3.0
```

To verify the installation, run

```
python -c "import tensorflow as tf;print(tf.reduce_sum(tf.random.normal([1000, 1000])))"
```

One should remember to activate the virtual environment every time he/she uses deepmd-kit.

### Install the DeePMD-kit's python interface

Execute

```
cd $deepmd_source_dir
pip install .
```

One may set the following environment variables before executing pip:

Environment variables	Allowed value	Default value	Usage
DP_VARIANT	cpu, cuda, rocm	cpu	Build CPU variant or GPU variant with CUDA or ROCM support.
CUDA_TOOLKIT_ROOT_PATH	Path	Detected automatically	The path to the CUDA toolkit directory.
ROCM_ROOT	Path	Detected automatically	The path to the ROCM toolkit directory.

To test the installation, one should firstly jump out of the source directory

```
cd /some/other/workspace
```

then execute

```
dp -h
```

It will print the help information like

```
usage: dp [-h] {train,freeze,test} ...

DeePMD-kit: A deep learning package for many-body potential energy
representation and molecular dynamics

optional arguments:
  -h, --help            show this help message and exit

Valid subcommands:
  {train,freeze,test}
    train                train a model
    freeze               freeze the model
    test                 test the model
```

## 1.2.2 Install the C++ interface

If one does not need to use DeePMD-kit with Lammmps or I-Pi, then the python interface installed in the previous section does everything and he/she can safely skip this section.

### Install the Tensorflow's C++ interface

Check the compiler version on your machine

```
gcc --version
```

The C++ interface of DeePMD-kit was tested with compiler gcc >= 4.8. It is noticed that the I-Pi support is only compiled with gcc >= 4.9.

First the C++ interface of Tensorflow should be installed. It is noted that the version of Tensorflow should be in consistent with the python interface. You may follow the instruction to install the corresponding C++ interface.

## Install the DeePMD-kit's C++ interface

Now goto the source code directory of DeePMD-kit and make a build place.

```
cd $deepmd_source_dir/source
mkdir build
cd build
```

I assume you want to install DeePMD-kit into path \$deepmd\_root, then execute cmake

```
cmake -DTENSORFLOW_ROOT=$tensorflow_root -DCMAKE_INSTALL_PREFIX=$deepmd_root ..
```

where the variable tensorflow\_root stores the location where the TensorFlow's C++ interface is installed.

One may add the following arguments to cmake:

CMake Arguments	Allowed value	Default value	Usage
-DTENSORFLOW_ROOT=<value>	Path	-	The Path to TensorFlow's C++ interface.
-DCMAKE_INSTALL_PREFIX=<value>	Path	-	The Path where DeePMD-kit will be installed.
-DUSE_CUDA_TOOLKIT=<value>	TRUE or FALSE	FALSE	If TRUE, Build GPU support with CUDA toolkit.
-DCUDA_TOOLKIT_ROOT_DIR=<value>	Path	Detected automatically	The path to the CUDA toolkit directory.
-DUSE_ROCM_TOOLKIT=<value>	TRUE or FALSE	FALSE	If TRUE, Build GPU support with ROCM toolkit.
-DROCM_ROOT=<value>	Path	Detected automatically	The path to the ROCM toolkit directory.

If the cmake has executed successfully, then

```
make -j4
make install
```

The option -j4 means using 4 processes in parallel. You may want to use a different number according to your hardware.

If everything works fine, you will have the following executable and libraries installed in \$deepmd\_root/bin and \$deepmd\_root/lib

```
$ ls $deepmd_root/bin
dp_ipi
$ ls $deepmd_root/lib
libdeepmd_ipi.so libdeepmd_op.so libdeepmd.so
```

### 1.2.3 Install LAMMPS's DeePMD-kit module

DeePMD-kit provide module for running MD simulation with LAMMPS. Now make the DeePMD-kit module for LAMMPS.

```
cd $deepmd_source_dir/source/build
make lammps
```

DeePMD-kit will generate a module called USER-DEEPM in the build directory. If you need low precision version, move `env_low.sh` to `env.sh` in the directory. Now download the LAMMPS code (29Oct2020 or later), and uncompress it:

```
cd /some/workspace
wget https://github.com/lammps/lammps/archive/stable_29Oct2020.tar.gz
tar xf stable_29Oct2020.tar.gz
```

The source code of LAMMPS is stored in directory `lammps-stable_29Oct2020`. Now go into the LAMMPS code and copy the DeePMD-kit module like this

```
cd lammps-stable_29Oct2020/src/
cp -r $deepmd_source_dir/source/build/USER-DEEPM .
```

Now build LAMMPS

```
make yes-kspace
make yes-user-deepmd
make mpi -j4
```

If everything works fine, you will end up with an executable `lmp_mpi`.

```
./lmp_mpi -h
```

The DeePMD-kit module can be removed from LAMMPS source code by

```
make no-user-deepmd
```

## 1.3 Install i-PI

The i-PI works in a client-server model. The i-PI provides the server for integrating the replica positions of atoms, while the DeePMD-kit provides a client named `dp_ipi` that computes the interactions (including energy, force and virial). The server and client communicates via the Unix domain socket or the Internet socket. A full instruction of i-PI can be found [here](#). The source code and a complete installation instructions of i-PI can be found [here](#). To use i-PI with already existing drivers, install and update using Pip:

```
pip install -U i-PI
```

Test with Pytest:

```
pip install pytest
pytest --pyargs ipi.tests
```

## 1.4 Building conda packages

One may want to keep both convenience and personalization of the DeePMD-kit. To achieve this goal, one can consider building conda packages. We provide building scripts in [deepmd-kit-recipes organization](#). These building tools are driven by [conda-build](#) and [conda-smithy](#).

For example, if one wants to turn on MPIIO package in LAMMPS, go to [lammps-dp-feedstock](#) repository and modify `recipe/build.sh`. `-D PKG_MPIIO=OFF` should be changed to `-D PKG_MPIIO=ON`. Then go to the main directory and executing

```
./build-locally.py
```

This requires the Docker has been installed. After the building, the packages will be generated in `build_artifacts/linux-64` and `build_artifacts/noarch`, and then one can install then executing

```
conda create -n deepmd lammps-dp -c file:///path/to/build_artifacts -c https://conda.
↳deepmodeling.org -c nvidia
```

One may also upload packages to one's Anaconda channel, so they can be installed on other machines:

```
anaconda upload /path/to/build_artifacts/linux-64/*.tar.bz2 /path/to/build_artifacts/
↳noarch/*.tar.bz2
```



## GETTING STARTED

In this text, we will call the deep neural network that is used to represent the interatomic interactions (Deep Potential) the **model**. The typical procedure of using DeePMD-kit is

1. *Prepare data*
2. *Train a model*
  - *Write the input script*
  - *Training*
  - *Parallel training*
  - *Training analysis with Tensorboard*
3. *Freeze a model*
4. *Test a model*
5. *Compress a model*
6. *Model inference*
  - *Python interface*
  - *C++ interface*
7. *Run MD*
  - *Run MD with LAMMPS*
  - *Run path-integral MD with i-PI*
  - *Use deep potential with ASE*
8. *Known limitations*

### 2.1 Prepare data

One needs to provide the following information to train a model: the atom type, the simulation box, the atom coordinate, the atom force, system energy and virial. A snapshot of a system that contains these information is called a **frame**. We use the following convention of units:

Property	Unit
Time	ps
Length	Å
Energy	eV
Force	eV/Å
Virial	eV
Pressure	Bar

The frames of the system are stored in two formats. A raw file is a plain text file with each information item written in one file and one frame written on one line. The default files that provide box, coordinate, force, energy and virial are `box.raw`, `coord.raw`, `force.raw`, `energy.raw` and `virial.raw`, respectively. *We recommend you use these file names.* Here is an example of `force.raw`:

```
$ cat force.raw
-0.724  2.039 -0.951  0.841 -0.464  0.363
 6.737  1.554 -5.587 -2.803  0.062  2.222
-1.968 -0.163  1.020 -0.225 -0.789  0.343
```

This `force.raw` contains 3 frames with each frame having the forces of 2 atoms, thus it has 3 lines and 6 columns. Each line provides all the 3 force components of 2 atoms in 1 frame. The first three numbers are the 3 force components of the first atom, while the second three numbers are the 3 force components of the second atom. The coordinate file `coord.raw` is organized similarly. In `box.raw`, the 9 components of the box vectors should be provided on each line. In `virial.raw`, the 9 components of the virial tensor should be provided on each line in the order `XX XY XZ YX YY YZ ZX ZY ZZ`. The number of lines of all raw files should be identical.

We assume that the atom types do not change in all frames. It is provided by `type.raw`, which has one line with the types of atoms written one by one. The atom types should be integers. For example the `type.raw` of a system that has 2 atoms with 0 and 1:

```
$ cat type.raw
0 1
```

Sometimes one needs to map the integer types to atom name. The mapping can be given by the file `type_map.raw`. For example

```
$ cat type_map.raw
0 H
```

The type 0 is named by "O" and the type 1 is named by "H".

The second format is the data sets of numpy binary data that are directly used by the training program. User can use the script `$deepmd_source_dir/data/raw/raw_to_set.sh` to convert the prepared raw files to data sets. For example, if we have a raw file that contains 6000 frames,

```
$ ls
box.raw coord.raw energy.raw force.raw type.raw virial.raw
$ $deepmd_source_dir/data/raw/raw_to_set.sh 2000
nframe is 6000
nline per set is 2000
will make 3 sets
making set 0 ...
making set 1 ...
making set 2 ...
```

(continues on next page)



(continued from previous page)

```
$ ls
box.raw coord.raw energy.raw force.raw set.000 set.001 set.002 type.raw virial.
↪raw
```

It generates three sets `set.000`, `set.001` and `set.002`, with each set contains 2000 frames. One do not need to take care of the binary data files in each of the `set.*` directories. The path containing `set.*` and `type.raw` is called a *system*.

### 2.1.1 Data preparation with dpdata

One can use the a convenient tool `dpdata` to convert data directly from the output of first priciples packages to the DeePMD-kit format. One may follow the [example](#) of using `dpdata` to find out how to use it.

## 2.2 Train a model

### 2.2.1 Write the input script

A model has two parts, a descriptor that maps atomic configuration to a set of symmetry invariant features, and a fitting net that takes descriptor as input and predicts the atomic contribution to the target physical property.

DeePMD-kit implements the following descriptors:

1. `se_e2_a`: DeepPot-SE constructed from all information (both angular and radial) of atomic configurations. The embedding takes the distance between atoms as input.
2. `se_e2_r`: DeepPot-SE constructed from radial information of atomic configurations. The embedding takes the distance between atoms as input.
3. `se_e3`: DeepPot-SE constructed from all information (both angular and radial) of atomic configurations. The embedding takes angles between two neighboring atoms as input.
4. `loc_frame`: Defines a local frame at each atom, and the compute the descriptor as local coordinates under this frame.
5. `hybrid`: Concatenate a list of descriptors to form a new descriptor.

The fitting of the following physical properties are supported

1. `ener`: Fitting the energy of the system. The force (derivative with atom positions) and the virial (derivative with the box tensor) can also be trained. See the [example](#).
2. `dipole`: The dipole moment.
3. `polar`: The polarizability.

## 2.2.2 Training

The training can be invoked by

```
$ dp train input.json
```

where `input.json` is the name of the input script. See the example for more details.

During the training, checkpoints will be written to files with prefix `save_ckpt` every `save_freq` training steps.

Several command line options can be passed to `dp train`, which can be checked with

```
$ dp train --help
```

An explanation will be provided

```
positional arguments:
  INPUT                the input json database

optional arguments:
  -h, --help            show this help message and exit
  --init-model INIT_MODEL
                        Initialize a model by the provided checkpoint
  --restart RESTART      Restart the training from the provided checkpoint
```

**--init-model model.ckpt**, initializes the model training with an existing model that is stored in the checkpoint `model.ckpt`, the network architectures should match.

**--restart model.ckpt**, continues the training from the checkpoint `model.ckpt`.

On some resources limited machines, one may want to control the number of threads used by DeePMD-kit. This is achieved by three environmental variables: `OMP_NUM_THREADS`, `TF_INTRA_OP_PARALLELISM_THREADS` and `TF_INTER_OP_PARALLELISM_THREADS`. `OMP_NUM_THREADS` controls the multithreading of DeePMD-kit implemented operations. `TF_INTRA_OP_PARALLELISM_THREADS` and `TF_INTER_OP_PARALLELISM_THREADS` controls `intra_op_parallelism_threads` and `inter_op_parallelism_threads`, which are Tensorflow configurations for multithreading. An explanation is found [here](#).

For example if you wish to use 3 cores of 2 CPUs on one node, you may set the environmental variables and run DeePMD-kit as follows:

```
export OMP_NUM_THREADS=6
export TF_INTRA_OP_PARALLELISM_THREADS=3
export TF_INTER_OP_PARALLELISM_THREADS=2
dp train input.json
```

One can set other environmental variables:

Environment variables	Allowed value	Default value	Usage
DP_INTERFACE_PREC	high, low	high	Control high (double) or low (float) precision of training.

### 2.2.3 Parallel training

Currently, parallel training is enabled in a synchronized way with help of [Horovod](#). DeePMD-kit will decide parallel training or not according to MPI context. Thus, there is no difference in your json/yaml input file.

Testing `examples/water/se_e2_a` on a 8-GPU host, linear acceleration can be observed with increasing number of cards.

Num of GPU cards	Seconds every 100 samples	Samples per second	Speed up
1	1.6116	62.05	1.00
2	1.6310	61.31	1.98
4	1.6168	61.85	3.99
8	1.6212	61.68	7.95

To experience this powerful feature, please install Horovod and `mpi4py` first. For better performance on GPU, please follow tuning steps in [Horovod on GPU](#).

```
# By default, MPI is used as communicator.
HOROVOD_WITHOUT_GLOO=1 HOROVOD_WITH_TENSORFLOW=1 pip install horovod mpi4py
```

Horovod works in the data-parallel mode resulting a larger global batch size. For example, the real batch size is 8 when `batch_size` is set to 2 in the input file and you launch 4 workers. Thus, `learning_rate` is automatically scaled by the number of workers for better convergence. Technical details of such heuristic rule are discussed at [Accurate, Large Minibatch SGD: Training ImageNet in 1 Hour](#).

With dependencies installed, have a quick try!

```
# Launch 4 processes on the same host
CUDA_VISIBLE_DEVICES=4,5,6,7 horovodrun -np 4 \
    dp train --mpi-log=workers input.json
```

Need to mention, environment variable `CUDA_VISIBLE_DEVICES` must be set to control parallelism on the occupied host where one process is bound to one GPU card.

What's more, 2 command-line arguments are defined to control the logging behavior.

```
optional arguments:
  -l LOG_PATH, --log-path LOG_PATH
                        set log file to log messages to disk, if not
                        specified, the logs will only be output to console
                        (default: None)
  -m {master,collect,workers}, --mpi-log {master,collect,workers}
                        Set the manner of logging when running with MPI.
                        'master' logs only on main process, 'collect'
                        broadcasts logs from workers to master and 'workers'
                        means each process will output its own log (default:
                        master)
```

## 2.2.4 Training analysis with Tensorboard

If enabled in json/yaml input file DeePMD-kit will create log files which can be used to analyze training procedure with Tensorboard. For a short tutorial please read this [document](#).

## 2.3 Freeze a model

The trained neural network is extracted from a checkpoint and dumped into a database. This process is called “freezing” a model. The idea and part of our code are from [Morgan](#). To freeze a model, typically one does

```
$ dp freeze -o graph.pb
```

in the folder where the model is trained. The output database is called `graph.pb`.

## 2.4 Test a model

The frozen model can be used in many ways. The most straightforward test can be performed using `dp test`. A typical usage of `dp test` is

```
dp test -m graph.pb -s /path/to/system -n 30
```

where `-m` gives the tested model, `-s` the path to the tested system and `-n` the number of tested frames. Several other command line options can be passed to `dp test`, which can be checked with

```
$ dp test --help
```

An explanation will be provided

```
usage: dp test [-h] [-m MODEL] [-s SYSTEM] [-S SET_PREFIX] [-n NUMB_TEST]
              [-r RAND_SEED] [--shuffle-test] [-d DETAIL_FILE]

optional arguments:
  -h, --help                show this help message and exit
  -m MODEL, --model MODEL    Frozen model file to import
  -s SYSTEM, --system SYSTEM The system dir
  -S SET_PREFIX, --set-prefix SET_PREFIX The set prefix
  -n NUMB_TEST, --numb-test NUMB_TEST The number of data for test
  -r RAND_SEED, --rand-seed RAND_SEED The random seed
  --shuffle-test             Shuffle test data
  -d DETAIL_FILE, --detail-file DETAIL_FILE The file containing details of energy force and virial accuracy
```

### 2.4.1 Calculate Model Deviation

One can also use a subcommand to calculate deviation of predicted forces or virials for a bunch of models in the following way:

```
dp model-devi -m graph.000.pb graph.001.pb graph.002.pb graph.003.pb -s ./data -o model_
→devi.out
```

where `-m` specifies graph files to be calculated, `-s` gives the data to be evaluated, `-o` the file to which model deviation results is dumped. Here is more information on this sub-command:

```
usage: dp model-devi [-h] [-v {DEBUG,3,INFO,2,WARNING,1,ERROR,0}]
                    [-l LOG_PATH] [-m MODELS [MODELS ...]] [-s SYSTEM]
                    [-S SET_PREFIX] [-o OUTPUT] [-f FREQUENCY] [-i ITEMS]

optional arguments:
  -h, --help            show this help message and exit
  -v {DEBUG,3,INFO,2,WARNING,1,ERROR,0}, --log-level {DEBUG,3,INFO,2,WARNING,1,ERROR,0}
                        set verbosity level by string or number, 0=ERROR,
                        1=WARNING, 2=INFO and 3=DEBUG (default: INFO)
  -l LOG_PATH, --log-path LOG_PATH
                        set log file to log messages to disk, if not
                        specified, the logs will only be output to console
                        (default: None)
  -m MODELS [MODELS ...], --models MODELS [MODELS ...]
                        Frozen models file to import (default:
                        ['graph.000.pb', 'graph.001.pb', 'graph.002.pb',
                        'graph.003.pb'])
  -s SYSTEM, --system SYSTEM
                        The system directory, not support recursive detection.
                        (default: .)
  -S SET_PREFIX, --set-prefix SET_PREFIX
                        The set prefix (default: set)
  -o OUTPUT, --output OUTPUT
                        The output file for results of model deviation
                        (default: model_devi.out)
  -f FREQUENCY, --frequency FREQUENCY
                        The trajectory frequency of the system (default: 1)
```

For more details with respect to definition of model deviation and its application, please refer to Yuzhi Zhang, Haidi Wang, Weijie Chen, Jinzhe Zeng, Linfeng Zhang, Han Wang, and Weinan E, DP-GEN: A concurrent learning platform for the generation of reliable deep learning based potential energy models, Computer Physics Communications, 2020, 253, 107206.

## 2.5 Compress a model

Once the frozen model is obtained from deepmd-kit, we can get the neural network structure and its parameters (weights, biases, etc.) from the trained model, and compress it in the following way:

```
dp compress input.json -i graph.pb -o graph-compress.pb
```

where input.json denotes the original training input script, -i gives the original frozen model, -o gives the compressed model. Several other command line options can be passed to dp compress, which can be checked with

```
$ dp compress --help
```

An explanation will be provided

```
usage: dp compress [-h] [-i INPUT] [-o OUTPUT] [-e EXTRAPOLATE] [-s STRIDE]
                  [-f FREQUENCY] [-d FOLDER]
                  INPUT

positional arguments:
  INPUT                The input parameter file in json or yaml format, which
                        should be consistent with the original model parameter
                        file

optional arguments:
  -h, --help            show this help message and exit
  -v {DEBUG,3,INFO,2,WARNING,1,ERROR,0}, --log-level {DEBUG,3,INFO,2,WARNING,1,ERROR,0}
                        set verbosity level by string or number, 0=ERROR,
                        1=WARNING, 2=INFO and 3=DEBUG (default: INFO)
  -l LOG_PATH, --log-path LOG_PATH
                        set log file to log messages to disk, if not
                        specified, the logs will only be output to console
                        (default: None)
  -m {master,collect,workers}, --mpi-log {master,collect,workers}
                        Set the manner of logging when running with MPI.
                        'master' logs only on main process, 'collect'
                        broadcasts logs from workers to master and 'workers'
                        means each process will output its own log (default:
                        master)
  -i INPUT, --input INPUT
                        The original frozen model, which will be compressed by
                        the code (default: frozen_model.pb)
  -o OUTPUT, --output OUTPUT
                        The compressed model (default:
                        frozen_model_compressed.pb)
  -s STEP, --step STEP  Model compression uses fifth-order polynomials to
                        interpolate the embedding-net. It introduces two
                        tables with different step size to store the
                        parameters of the polynomials. The first table covers
                        the range of the training data, while the second table
                        is an extrapolation of the training data. The domain
                        of each table is uniformly divided by a given step
                        size. And the step(parameter) denotes the step size of
                        the first table and the second table will use 10 *
```

(continues on next page)

(continued from previous page)

```

        step as it's step size to save the memory. Usually the
        value ranges from 0.1 to 0.001. Smaller step means
        higher accuracy and bigger model size (default: 0.01)
-e EXTRAPOLATE, --extrapolate EXTRAPOLATE
    The domain range of the first table is automatically
    detected by the code: [d_low, d_up]. While the second
    table ranges from the first table's upper
    boundary(d_up) to the extrapolate(parameter) * d_up:
    [d_up, extrapolate * d_up] (default: 5)
-f FREQUENCY, --frequency FREQUENCY
    The frequency of tabulation overflow check(Whether the
    input environment matrix overflow the first or second
    table range). By default do not check the overflow
    (default: -1)
-c CHECKPOINT_FOLDER, --checkpoint-folder CHECKPOINT_FOLDER
    path to checkpoint folder (default: .)

```

### Parameter explanation

Model compression, which including tabulating the embedding-net. The table is composed of fifth-order polynomial coefficients and is assembled from two sub-tables. The first sub-table takes the stride(parameter) as it's uniform stride, while the second sub-table takes  $10 * \text{stride}$  as it's uniform stride. The range of the first table is automatically detected by deepmd-kit, while the second table ranges from the first table's upper boundary(upper) to the extrapolate(parameter) \* upper. Finally, we added a check frequency parameter. It indicates how often the program checks for overflow(if the input environment matrix overflow the first or second table range) during the MD inference.

### Justification of model compression

Model compression, with little loss of accuracy, can greatly speed up MD inference time. According to different simulation systems and training parameters, the speedup can reach more than 10 times at both CPU and GPU devices. At the same time, model compression can greatly change the memory usage, reducing as much as 20 times under the same hardware conditions.

### Acceptable original model version

The model compression method requires that the version of DeePMD-kit used in original model generation should be 1.3 or above. If one has a frozen 1.2 model, one can first use the convenient conversion interface of DeePMD-kit-v1.2.4 to get a 1.3 executable model.(eg: `dp convert-to-1.3 -i frozen_1.2.pb -o frozen_1.3.pb`)

## 2.6 Model inference

Note that the model for inference is required to be compatible with the DeePMD-kit package. See Model compatibility for details.

### 2.6.1 Python interface

One may use the python interface of DeePMD-kit for model inference, an example is given as follows

```
from deepmd.infer import DeepPot
import numpy as np
dp = DeepPot('graph.pb')
coord = np.array([[1,0,0], [0,0,1.5], [1,0,3]]).reshape([1, -1])
cell = np.diag(10 * np.ones(3)).reshape([1, -1])
atype = [1,0,1]
e, f, v = dp.eval(coord, cell, atype)
```

where e, f and v are predicted energy, force and virial of the system, respectively.

Furthermore, one can use the python interface to calculate model deviation.

```
from deepmd.infer import calc_model_devi
from deepmd.infer import DeepPot as DP
import numpy as np

coord = np.array([[1,0,0], [0,0,1.5], [1,0,3]]).reshape([1, -1])
cell = np.diag(10 * np.ones(3)).reshape([1, -1])
atype = [1,0,1]
graphs = [DP("graph.000.pb"), DP("graph.001.pb")]
model_devi = calc_model_devi(coord, cell, atype, graphs)
```

### 2.6.2 C++ interface

The C++ interface of DeePMD-kit is also available for model interface, which is considered faster than Python interface. An example `infer_water.cpp` is given below:

```
#include "deepmd/DeepPot.h"

int main(){
    deepmd::DeepPot dp ("graph.pb");
    std::vector<double> coord = {1., 0., 0., 0., 0., 1.5, 1., 0., 3.};
    std::vector<double> cell = {10., 0., 0., 0., 10., 0., 0., 0., 10.};
    std::vector<int> atype = {1, 0, 1};
    double e;
    std::vector<double> f, v;
    dp.compute (e, f, v, coord, atype, cell);
}
```

where e, f and v are predicted energy, force and virial of the system, respectively.

You can compile `infer_water.cpp` using gcc:



```
gcc infer_water.cpp -D HIGH_PREC -L $deepmd_root/lib -L $tensorflow_root/lib -I $deepmd_
↳root/include -I $tensorflow_root/include -Wl,--no-as-needed -ldeepmd_op -ldeepmd -
↳ldeepmd_cc -ltensorflow_cc -ltensorflow_framework -lstdc++ -Wl,-rpath=$deepmd_root/lib
↳-Wl,-rpath=$tensorflow_root/lib -o infer_water
```

and then run the program:

```
./infer_water
```

## 2.7 Run MD

Note that the model for MD simulations is required to be compatible with the DeePMD-kit package. See Model compatibility for details.

### 2.7.1 Run MD with LAMMPS

Include deepmd in the pair\_style

#### Syntax

```
pair_style deepmd models ... keyword value ...
```

- deepmd = style of this pair\_style
- models = frozen model(s) to compute the interaction. If multiple models are provided, then the model deviation will be computed
- keyword = *out\_file* or *out\_freq* or *fparam* or *atomic* or *relative*

#### Examples

```
pair_style deepmd graph.pb
pair_style deepmd graph.pb fparam 1.2
pair_style deepmd graph_0.pb graph_1.pb graph_2.pb out_file md.out out_freq 10 atomic
↳relative 1.0
```

#### Description

Evaluate the interaction of the system by using [Deep Potential](#) or [Deep Potential Smooth Edition](#). It is noticed that deep potential is not a “pairwise” interaction, but a multi-body interaction.

This pair style takes the deep potential defined in a model file that usually has the .pb extension. The model can be trained and frozen by package [DeePMD-kit](#).

The model deviation evaluate the consistency of the force predictions from multiple models. By default, only the maximal, minimal and average model deviations are output. If the key `atomic` is set, then the model deviation of force prediction of each atom will be output.

By default, the model deviation is output in absolute value. If the keyword `relative` is set, then the relative model deviation will be output. The relative model deviation of the force on atom *i* is defined by

$$E_{f,i} = \frac{|D_{f,i}|}{|f_i| + \text{level}}$$

where  $D_{f,i}$  is the absolute model deviation of the force on atom  $i$ ,  $|f_i|$  is the norm of the force and `level` is provided as the parameter of the keyword `relative`.

## Restrictions

- The `deepmd` pair style is provided in the USER-DEEPMO package, which is compiled from the DeePMD-kit, visit the [DeePMD-kit website](#) for more information.

## Long-range interaction

The reciprocal space part of the long-range interaction can be calculated by LAMMPS command `kpace_style`. To use it with DeePMD-kit, one writes

```
pair_style      deepmd graph.pb
pair_coeff
kpace_style     pppm 1.0e-5
kpace_modify    gewald 0.45
```

Please notice that the DeePMD does nothing to the direct space part of the electrostatic interaction, because this part is assumed to be fitted in the DeePMD model (the direct space cut-off is thus the cut-off of the DeePMD model). The splitting parameter `gewald` is modified by the `kpace_modify` command.

## 2.7.2 Run path-integral MD with i-PI

The i-PI works in a client-server model. The i-PI provides the server for integrating the replica positions of atoms, while the DeePMD-kit provides a client named `dp_ipi` (or `dp_ipi_low` for low precision) that computes the interactions (including energy, force and virial). The server and client communicates via the Unix domain socket or the Internet socket. Installation instructions of i-PI can be found [here](#). The client can be started by

```
i-pi input.xml &
dp_ipi water.json
```

It is noted that multiple instances of the client is allow for computing, in parallel, the interactions of multiple replica of the path-integral MD.

`water.json` is the parameter file for the client `dp_ipi`, and an example is provided:

```
{
  "verbose":          false,
  "use_unix":         true,
  "port":             31415,
  "host":             "localhost",
  "graph_file":       "graph.pb",
  "coord_file":       "conf.xyz",
  "atom_type" : {
    "OW":             0,
    "HW1":            1,
```

(continues on next page)

(continued from previous page)

```

    "HW2": 1
}
}

```

The option **use\_unix** is set to **true** to activate the Unix domain socket, otherwise, the Internet socket is used.

The option **port** should be the same as that in input.xml:

```
<port>31415</port>
```

The option **graph\_file** provides the file name of the frozen model.

The **dp\_ipi** gets the atom names from an **XYZ file** provided by **coord\_file** (meanwhile ignores all coordinates in it), and translates the names to atom types by rules provided by **atom\_type**.

## 2.7.3 Use deep potential with ASE

Deep potential can be set up as a calculator with ASE to obtain potential energies and forces.

```

from ase import Atoms
from deepmd.calculator import DP

water = Atoms('H2O',
               positions=[(0.7601, 1.9270, 1),
                           (1.9575, 1, 1),
                           (1., 1., 1.)],
               cell=[100, 100, 100],
               calculator=DP(model="frozen_model.pb"))
print(water.get_potential_energy())
print(water.get_forces())

```

Optimization is also available:

```

from ase.optimize import BFGS
dyn = BFGS(water)
dyn.run(fmax=1e-6)
print(water.get_positions())

```

## 2.8 Known limitations

If you use deepmd-kit in a GPU environment, the acceptable value range of some variables are additionally restricted compared to the CPU environment due to the software's GPU implementations:

1. The number of atom type of a given system must be less than 128.
2. The maximum distance between an atom and its neighbors must be less than 128. It can be controlled by setting the **rcut** value of training parameters.
3. Theoretically, the maximum number of atoms that a single GPU can accept is about 10,000,000. However, this value is actually limited by the GPU memory size currently, usually within 1000,000 atoms even at the model compression mode.
4. The total **sel** value of training parameters(in model/descriptor section) must be less than 4096.



## TENSORBOARD USAGE

TensorBoard provides the visualization and tooling needed for machine learning experimentation. A full instruction of tensorboard can be found [here](#).

### 3.1 Highlighted features

DeePMD-kit can now use most of the interesting features enabled by tensorboard!

- **Tracking and visualizing metrics**, such as l2\_loss, l2\_energy\_loss and l2\_force\_loss
- **Visualizing the model graph** (ops and layers)
- **Viewing histograms of weights, biases, or other tensors as they change over time.**
- **Viewing summaries of trainable variables**

### 3.2 How to use Tensorboard with DeePMD-kit

Before running TensorBoard, make sure you have generated summary data in a log directory by modifying the the input script, set “tensorboard” true in training subsection will enable the tensorboard data analysis. eg. **water\_se\_a.json**.

```
"training" : {
  "systems":      ["../data/"],
  "set_prefix":   "set",
  "stop_batch":   1000000,
  "batch_size":   1,

  "seed":         1,

  "_comment": " display and restart",
  "_comment": " frequencies counted in batch",
  "disp_file":    "lcurve.out",
  "disp_freq":    100,
  "numb_test":    10,
  "save_freq":    1000,
  "save_ckpt":    "model.ckpt",
  "load_ckpt":    "model.ckpt",
  "disp_training": true,
  "time_training": true,
  "tensorboard":  true,
```

(continues on next page)

(continued from previous page)

```
"tensorboard_log_dir": "log",  
"profiling": false,  
"profiling_file": "timeline.json",  
"_comment": "that's all"  
}
```

Once you have event files, run TensorBoard and provide the log directory. This should print that TensorBoard has started. Next, connect to `http://tensorboard_server_ip:6006`.

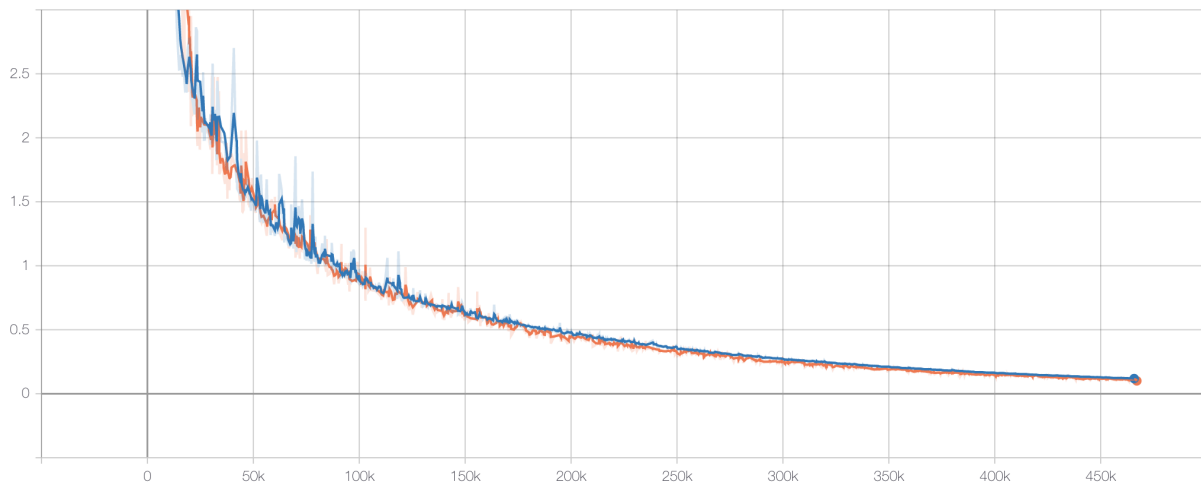
TensorBoard requires a logdir to read logs from. For info on configuring TensorBoard, run `tensorboard --help`. One can easily change the log name with “`tensorboard_log_dir`”.

```
tensorboard --logdir path/to/logs
```

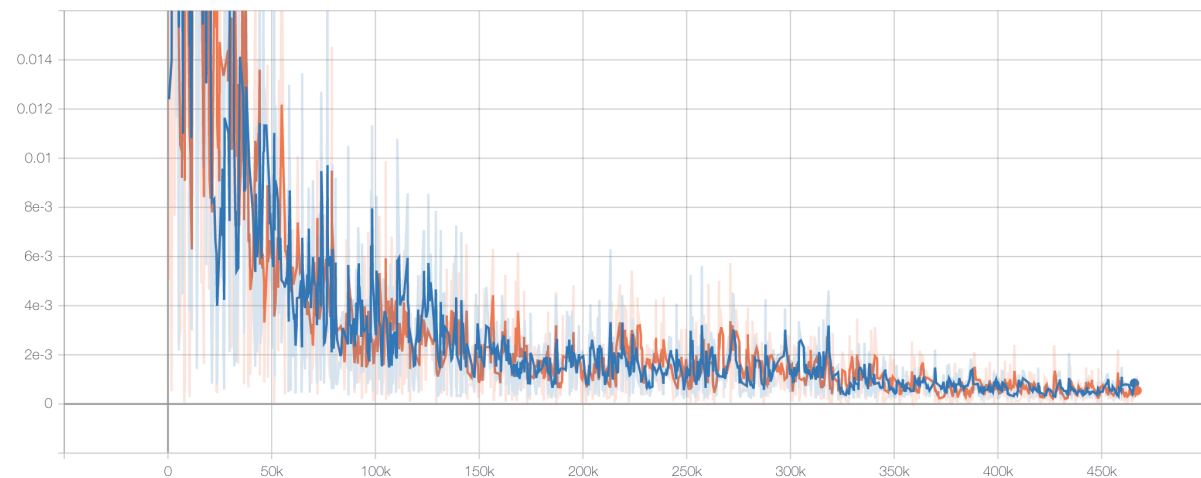
## 3.3 Examples

### 3.3.1 Tracking and visualizing loss metrics(red:train, blue:test)

l2\_loss

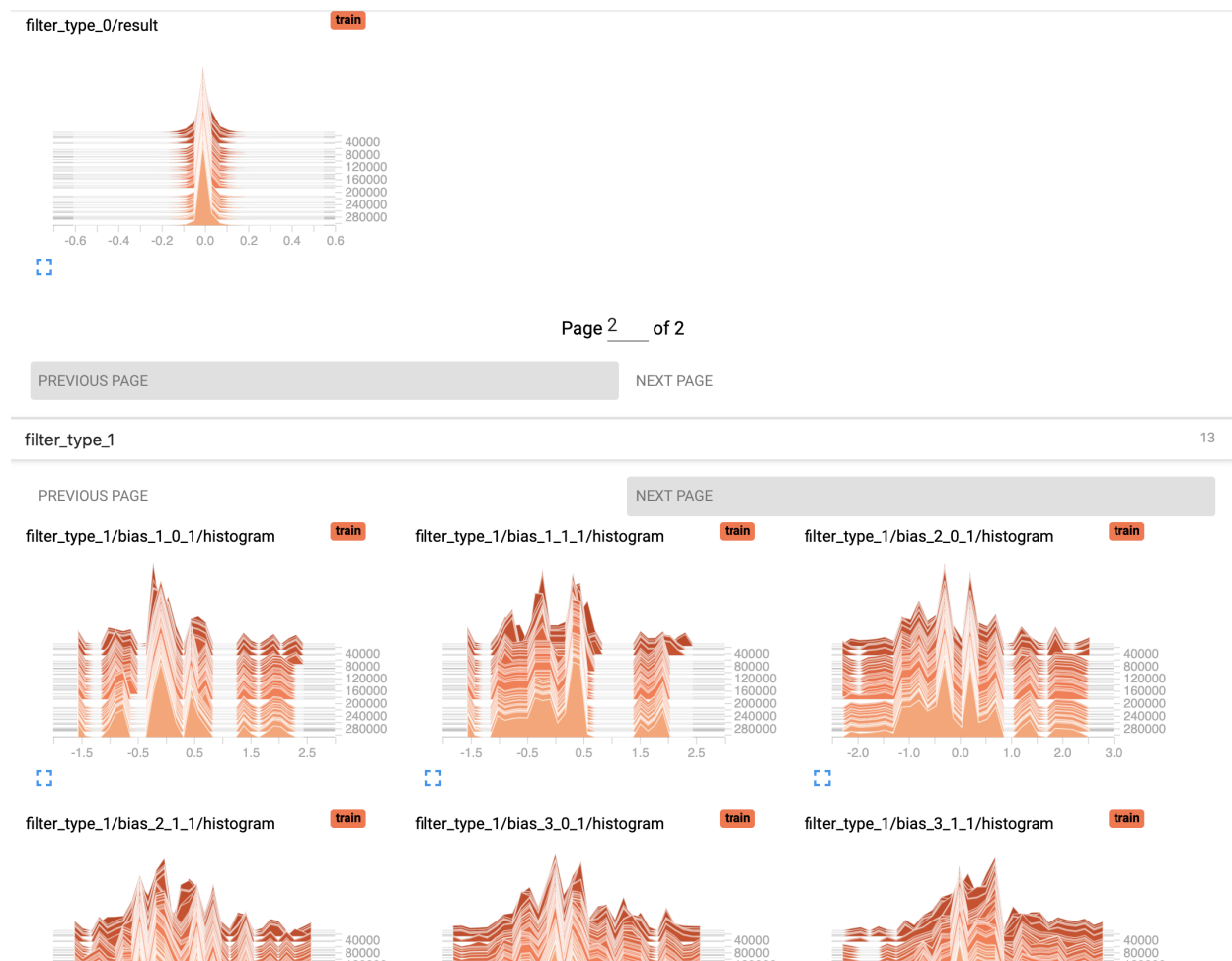


l2\_ener\_loss





### 3.3.3 Viewing histograms of weights, biases, or other tensors as they change over time





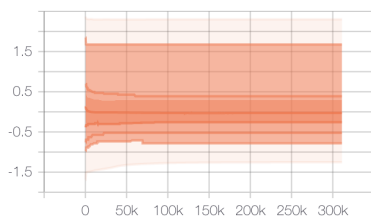
filter\_type\_0

13

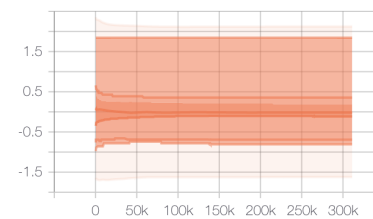
PREVIOUS PAGE

NEXT PAGE

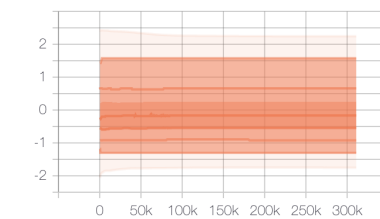
filter\_type\_0/bias\_1\_0\_1/histogram



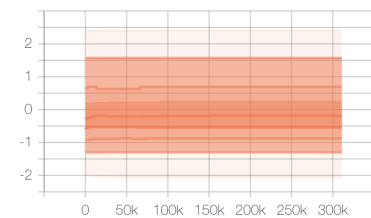
train filter\_type\_0/bias\_1\_1\_1/histogram



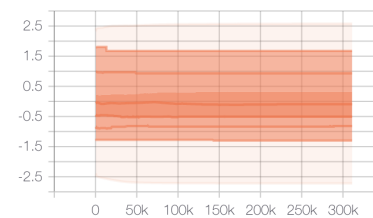
train filter\_type\_0/bias\_2\_0\_1/histogram



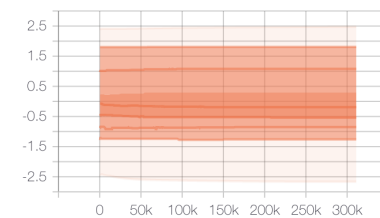
filter\_type\_0/bias\_2\_1\_1/histogram



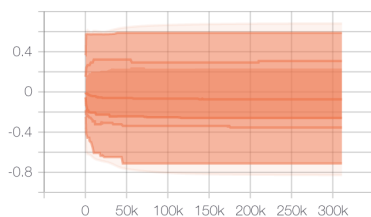
train filter\_type\_0/bias\_3\_0\_1/histogram



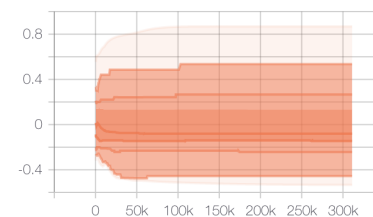
train filter\_type\_0/bias\_3\_1\_1/histogram



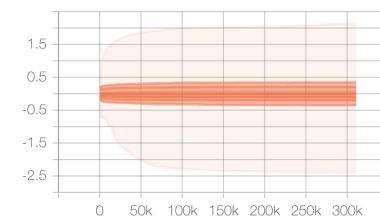
filter\_type\_0/matrix\_1\_0\_1/histogram



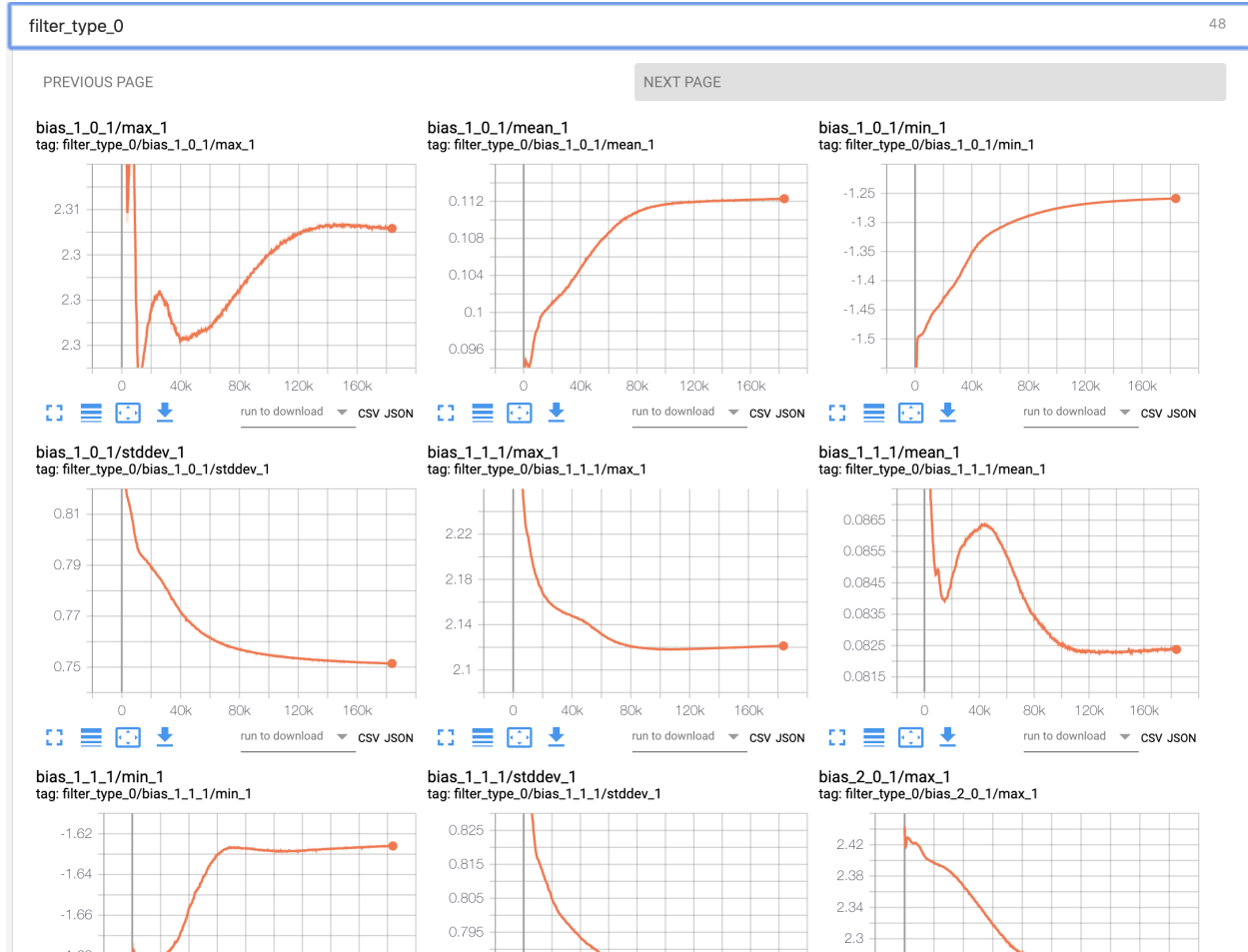
train filter\_type\_0/matrix\_1\_1\_1/histogram



train filter\_type\_0/matrix\_2\_0\_1/histogram



### 3.3.4 Viewing summaries of trainable variables



## 3.4 Attention

Allowing the tensorboard analysis will takes extra execution time.(eg, 15% increasing @Nvidia GTX 1080Ti double precision with default water sample)

**TensorBoard can be used in Google Chrome or Firefox.** Other browsers might work, but there may be bugs or performance issues.

In consequence of various differences of computers or systems, problems may occur. Some common circumstances are listed as follows. In addition, some frequently asked questions about parameters setting are listed as follows. If other unexpected problems occur, you're welcome to contact us for help.

## 4.1 Trouble shooting

- Installation
- Model compatibility
- MD: cannot run LAMMPS after installing a new version of DeePMD-kit
- The temperature undulates violently during early stages of MD

## 4.2 Parameters setting

- Do we need to set  $rcut < \text{half boxsize}$  ?
- How to control the number of nodes used by a job ?
- How to set  $sel$  ?
- How to tune Fitting/embedding-net size ?



In this example we will convert the DFT labeled data stored in VASP OUTCAR format into the data format used by DeePMD-kit. The example OUTCAR can be found in the directory.

```
$deepmd_source_dir/examples/data_conv
```

## 5.1 Definition

The DeePMD-kit organize data in **systems**. Each **system** is composed by a number of **frames**. One may roughly view a **frame** as a snap short on an MD trajectory, but it does not necessary come from an MD simulation. A **frame** records the coordinates and types of atoms, cell vectors if the periodic boundary condition is assumed, energy, atomic forces and virial. It is noted that the **frames** in one **system** share the same number of atoms with the same type.

## 5.2 Data conversion

It is convenient to use `dpdata` to convert data generated by DFT packages to the data format used by DeePMD-kit.

To install one can execute

```
pip install dpdata
```

An example of converting data **VASP** data in OUTCAR format to DeePMD-kit data can be found at

```
$deepmd_source_dir/examples/data_conv
```

Switch to that directory, then one can convert data by using the following python script

```
import dpdata
dsys = dpdata.LabeledSystem('OUTCAR')
dsys.to('deepmd/npz', 'deepmd_data', set_size = dsys.get_nframes())
```

`get_nframes()` method gets the number of frames in the OUTCAR, and the argument `set_size` enforces that the set size is equal to the number of frames in the system, viz. only one **set** is created in the **system**.

The data in DeePMD-kit format is stored in the folder `deepmd_data`.

A list of all [supported data format](#) and more nice features of `dpdata` can be found at the [official website](#).



## TRAINING PARAMETERS

### **model:**

type: dict

argument path: model

### **type\_map:**

type: list, optional

argument path: model/type\_map

A list of strings. Give the name to each type of atoms. It is noted that the number of atom type of training system must be less than 128 in a GPU environment.

### **data\_stat\_nbatch:**

type: int, optional, default: 10

argument path: model/data\_stat\_nbatch

The model determines the normalization from the statistics of the data. This key specifies the number of *frames* in each *system* used for statistics.

### **data\_stat\_protect:**

type: float, optional, default: 0.01

argument path: model/data\_stat\_protect

Protect parameter for atomic energy regression.

### **use\_srtab:**

type: str, optional

argument path: model/use\_srtab

The table for the short-range pairwise interaction added on top of DP. The table is a text data file with  $(N_t + 1) * N_t / 2 + 1$  columns. The first column is the distance between atoms. The second to the last columns are energies for pairs of certain types. For example we have two atom types, 0 and 1. The columns from 2nd to 4th are for 0-0, 0-1 and 1-1 correspondingly.

### **smin\_alpha:**

type: float, optional

argument path: model/smin\_alpha

The short-range tabulated interaction will be swithed according to the distance of the nearest neighbor. This distance is calculated by softmin. This parameter is the decaying parameter in the softmin. It is only required when *use\_srtab* is provided.

### **sw\_rmin:**

type: float, optional  
argument path: model/sw\_rmin

The lower boundary of the interpolation between short-range tabulated interaction and DP. It is only required when *use\_srtab* is provided.

**sw\_rmax:**

type: float, optional  
argument path: model/sw\_rmax

The upper boundary of the interpolation between short-range tabulated interaction and DP. It is only required when *use\_srtab* is provided.

**type\_embedding:**

type: dict, optional  
argument path: model/type\_embedding

The type embedding.

**neuron:**

type: list, optional, default: [2, 4, 8]  
argument path: model/type\_embedding/neuron

Number of neurons in each hidden layers of the embedding net. When two layers are of the same size or one layer is twice as large as the previous layer, a skip connection is built.

**activation\_function:**

type: str, optional, default: tanh  
argument path: model/type\_embedding/activation\_function

The activation function in the embedding net. Supported activation functions are “relu”, “relu6”, “softplus”, “sigmoid”, “tanh”, “gelu”.

**resnet\_dt:**

type: bool, optional, default: False  
argument path: model/type\_embedding/resnet\_dt

Whether to use a “Timestep” in the skip connection

**precision:**

type: str, optional, default: float64  
argument path: model/type\_embedding/precision

The precision of the embedding net parameters, supported options are “default”, “float16”, “float32”, “float64”.

**trainable:**

type: bool, optional, default: True  
argument path: model/type\_embedding/trainable

If the parameters in the embedding net are trainable

**seed:**

type: int | NoneType, optional  
argument path: model/type\_embedding/seed

Random seed for parameter initialization



**descriptor:**

type: dict

argument path: model/descriptor

The descriptor of atomic environment.

Depending on the value of *type*, different sub args are accepted.

**type:**

type: str (flag key)

argument path: model/descriptor/type

possible choices: *loc\_frame*, *se\_e2\_a*, *se\_e2\_r*, *se\_e3*, *se\_a\_tpe*, *hybrid*

The type of the descriptor. See explanation below.

- *loc\_frame*: Defines a local frame at each atom, and the compute the descriptor as local coordinates under this frame.
- *se\_e2\_a*: Used by the smooth edition of Deep Potential. The full relative coordinates are used to construct the descriptor.
- *se\_e2\_r*: Used by the smooth edition of Deep Potential. Only the distance between atoms is used to construct the descriptor.
- *se\_e3*: Used by the smooth edition of Deep Potential. The full relative coordinates are used to construct the descriptor. Three-body embedding will be used by this descriptor.
- *se\_a\_tpe*: Used by the smooth edition of Deep Potential. The full relative coordinates are used to construct the descriptor. Type embedding will be used by this descriptor.
- *hybrid*: Concatenate of a list of descriptors as a new descriptor.

When *type* is set to *loc\_frame*:

**sel\_a:**

type: list

argument path: model/descriptor[loc\_frame]/sel\_a

A list of integers. The length of the list should be the same as the number of atom types in the system. *sel\_a[i]* gives the selected number of type-*i* neighbors. The full relative coordinates of the neighbors are used by the descriptor.

**sel\_r:**

type: list

argument path: model/descriptor[loc\_frame]/sel\_r

A list of integers. The length of the list should be the same as the number of atom types in the system. *sel\_r[i]* gives the selected number of type-*i* neighbors. Only relative distance of the neighbors are used by the descriptor. *sel\_a[i] + sel\_r[i]* is recommended to be larger than the maximally possible number of type-*i* neighbors in the cut-off radius.

**rcut:**

type: float, optional, default: 6.0

argument path: model/descriptor[loc\_frame]/rcut

The cut-off radius. The default value is 6.0

**axis\_rule:**

type: list

argument path: `model/descriptor[loc_frame]/axis_rule`

A list of integers. The length should be 6 times of the number of types.

- `axis_rule[i*6+0]`: class of the atom defining the first axis of type-*i* atom. 0 for neighbors with full coordinates and 1 for neighbors only with relative distance.
- `axis_rule[i*6+1]`: type of the atom defining the first axis of type-*i* atom.
- `axis_rule[i*6+2]`: index of the axis atom defining the first axis. Note that the neighbors with the same class and type are sorted according to their relative distance.
- `axis_rule[i*6+3]`: class of the atom defining the first axis of type-*i* atom. 0 for neighbors with full coordinates and 1 for neighbors only with relative distance.
- `axis_rule[i*6+4]`: type of the atom defining the second axis of type-*i* atom.
- `axis_rule[i*6+5]`: class of the atom defining the second axis of type-*i* atom. 0 for neighbors with full coordinates and 1 for neighbors only with relative distance.

When `type` is set to `se_e2_a` (or its alias `se_a`):

**sel:**

type: `list | str`, optional, default: `auto`

argument path: `model/descriptor[se_e2_a]/sel`

This parameter set the number of selected neighbors for each type of atom. It can be:

- *List[int]*. The length of the list should be the same as the number of atom types in the system. *sel[i]* gives the selected number of type-*i* neighbors. *sel[i]* is recommended to be larger than the maximally possible number of type-*i* neighbors in the cut-off radius. It is noted that the total sel value must be less than 4096 in a GPU environment.
- *str*. Can be “auto:factor” or “auto”. “factor” is a float number larger than 1. This option will automatically determine the *sel*. In detail it counts the maximal number of neighbors with in the cutoff radius for each type of neighbor, then multiply the maximum by the “factor”. Finally the number is wrapped up to 4 divisible. The option “auto” is equivalent to “auto:1.1”.

**rcut:**

type: `float`, optional, default: `6.0`

argument path: `model/descriptor[se_e2_a]/rcut`

The cut-off radius.

**rcut\_smth:**

type: `float`, optional, default: `0.5`

argument path: `model/descriptor[se_e2_a]/rcut_smth`

Where to start smoothing. For example the  $1/r$  term is smoothed from *rcut* to *rcut\_smth*

**neuron:**

type: `list`, optional, default: `[10, 20, 40]`

argument path: `model/descriptor[se_e2_a]/neuron`

Number of neurons in each hidden layers of the embedding net. When two layers are of the same size or one layer is twice as large as the previous layer, a skip connection is built.

**axis\_neuron:**

type: `int`, optional, default: `4`

argument path: `model/descriptor[se_e2_a]/axis_neuron`

Size of the submatrix of G (embedding matrix).

**activation\_function:**

type: str, optional, default: tanh

argument path: model/descriptor[se\_e2\_a]/activation\_function

The activation function in the embedding net. Supported activation functions are “relu”, “relu6”, “softplus”, “sigmoid”, “tanh”, “gelu”.

**resnet\_dt:**

type: bool, optional, default: False

argument path: model/descriptor[se\_e2\_a]/resnet\_dt

Whether to use a “Timestep” in the skip connection

**type\_one\_side:**

type: bool, optional, default: False

argument path: model/descriptor[se\_e2\_a]/type\_one\_side

Try to build  $N_{\text{types}}$  embedding nets. Otherwise, building  $N_{\text{types}}^2$  embedding nets

**precision:**

type: str, optional, default: float64

argument path: model/descriptor[se\_e2\_a]/precision

The precision of the embedding net parameters, supported options are “default”, “float16”, “float32”, “float64”.

**trainable:**

type: bool, optional, default: True

argument path: model/descriptor[se\_e2\_a]/trainable

If the parameters in the embedding net is trainable

**seed:**

type: int | NoneType, optional

argument path: model/descriptor[se\_e2\_a]/seed

Random seed for parameter initialization

**exclude\_types:**

type: list, optional, default: []

argument path: model/descriptor[se\_e2\_a]/exclude\_types

The Excluded types

**set\_davg\_zero:**

type: bool, optional, default: False

argument path: model/descriptor[se\_e2\_a]/set\_davg\_zero

Set the normalization average to zero. This option should be set when *atom\_ener* in the energy fitting is used

When `type` is set to `se_e2_r` (or its alias `se_r`):

**sel:**

type: list | str, optional, default: auto

argument path: `model/descriptor[se_e2_r]/sel`

This parameter set the number of selected neighbors for each type of atom. It can be:

- *List[int]*. The length of the list should be the same as the number of atom types in the system. *sel[i]* gives the selected number of type-i neighbors. *sel[i]* is recommended to be larger than the maximally possible number of type-i neighbors in the cut-off radius. It is noted that the total sel value must be less than 4096 in a GPU environment.
- *str*. Can be “auto:factor” or “auto”. “factor” is a float number larger than 1. This option will automatically determine the *sel*. In detail it counts the maximal number of neighbors with in the cutoff radius for each type of neighbor, then multiply the maximum by the “factor”. Finally the number is wrapped up to 4 divisible. The option “auto” is equivalent to “auto:1.1”.

#### **rcut:**

type: float, optional, default: 6.0

argument path: `model/descriptor[se_e2_r]/rcut`

The cut-off radius.

#### **rcut\_smth:**

type: float, optional, default: 0.5

argument path: `model/descriptor[se_e2_r]/rcut_smth`

Where to start smoothing. For example the  $1/r$  term is smoothed from *rcut* to *rcut\_smth*

#### **neuron:**

type: list, optional, default: [10, 20, 40]

argument path: `model/descriptor[se_e2_r]/neuron`

Number of neurons in each hidden layers of the embedding net. When two layers are of the same size or one layer is twice as large as the previous layer, a skip connection is built.

#### **activation\_function:**

type: str, optional, default: tanh

argument path: `model/descriptor[se_e2_r]/activation_function`

The activation function in the embedding net. Supported activation functions are “relu”, “relu6”, “softplus”, “sigmoid”, “tanh”, “gelu”.

#### **resnet\_dt:**

type: bool, optional, default: False

argument path: `model/descriptor[se_e2_r]/resnet_dt`

Whether to use a “Timestep” in the skip connection

#### **type\_one\_side:**

type: bool, optional, default: False

argument path: `model/descriptor[se_e2_r]/type_one_side`

Try to build  $N_{types}$  embedding nets. Otherwise, building  $N_{types}^2$  embedding nets

#### **precision:**

type: str, optional, default: float64

argument path: `model/descriptor[se_e2_r]/precision`

The precision of the embedding net parameters, supported options are “default”, “float16”, “float32”, “float64”.

**trainable:**

type: bool, optional, default: True

argument path: model/descriptor[se\_e2\_r]/trainable

If the parameters in the embedding net are trainable

**seed:**

type: int | NoneType, optional

argument path: model/descriptor[se\_e2\_r]/seed

Random seed for parameter initialization

**exclude\_types:**

type: list, optional, default: []

argument path: model/descriptor[se\_e2\_r]/exclude\_types

The Excluded types

**set\_davg\_zero:**

type: bool, optional, default: False

argument path: model/descriptor[se\_e2\_r]/set\_davg\_zero

Set the normalization average to zero. This option should be set when *atom\_ener* in the energy fitting is used

When `type` is set to `se_e3` (or its aliases `se_at`, `se_a_3be`, `se_t`):

**sel:**

type: list | str, optional, default: auto

argument path: model/descriptor[se\_e3]/sel

This parameter set the number of selected neighbors for each type of atom. It can be:

- *List[int]*. The length of the list should be the same as the number of atom types in the system. *sel[i]* gives the selected number of type-i neighbors. *sel[i]* is recommended to be larger than the maximally possible number of type-i neighbors in the cut-off radius. It is noted that the total sel value must be less than 4096 in a GPU environment.
- *str*. Can be “auto:factor” or “auto”. “factor” is a float number larger than 1. This option will automatically determine the *sel*. In detail it counts the maximal number of neighbors with in the cutoff radius for each type of neighbor, then multiply the maximum by the “factor”. Finally the number is wrapped up to 4 divisible. The option “auto” is equivalent to “auto:1.1”.

**rcut:**

type: float, optional, default: 6.0

argument path: model/descriptor[se\_e3]/rcut

The cut-off radius.

**rcut\_smth:**

type: float, optional, default: 0.5

argument path: model/descriptor[se\_e3]/rcut\_smth

Where to start smoothing. For example the  $1/r$  term is smoothed from *rcut* to *rcut\_smth*

**neuron:**

type: list, optional, default: [10, 20, 40]

argument path: `model/descriptor[se_e3]/neuron`

Number of neurons in each hidden layers of the embedding net. When two layers are of the same size or one layer is twice as large as the previous layer, a skip connection is built.

**activation\_function:**

type: `str`, optional, default: `tanh`

argument path: `model/descriptor[se_e3]/activation_function`

The activation function in the embedding net. Supported activation functions are “relu”, “relu6”, “softplus”, “sigmoid”, “tanh”, “gelu”.

**resnet\_dt:**

type: `bool`, optional, default: `False`

argument path: `model/descriptor[se_e3]/resnet_dt`

Whether to use a “Timestep” in the skip connection

**precision:**

type: `str`, optional, default: `float64`

argument path: `model/descriptor[se_e3]/precision`

The precision of the embedding net parameters, supported options are “default”, “float16”, “float32”, “float64”.

**trainable:**

type: `bool`, optional, default: `True`

argument path: `model/descriptor[se_e3]/trainable`

If the parameters in the embedding net are trainable

**seed:**

type: `int | NoneType`, optional

argument path: `model/descriptor[se_e3]/seed`

Random seed for parameter initialization

**set\_davg\_zero:**

type: `bool`, optional, default: `False`

argument path: `model/descriptor[se_e3]/set_davg_zero`

Set the normalization average to zero. This option should be set when *atom\_ener* in the energy fitting is used

When `type` is set to `se_a_tpe` (or its alias `se_a_ebd`):

**sel:**

type: `list | str`, optional, default: `auto`

argument path: `model/descriptor[se_a_tpe]/sel`

This parameter set the number of selected neighbors for each type of atom. It can be:

- `List[int]`. The length of the list should be the same as the number of atom types in the system. `sel[i]` gives the selected number of type-i neighbors. `sel[i]` is recommended to be larger than the maximally possible number of type-i neighbors in the cut-off radius. It is noted that the total sel value must be less than 4096 in a GPU environment.

- *str*. Can be “auto:factor” or “auto”. “factor” is a float number larger than 1. This option will automatically determine the *sel*. In detail it counts the maximal number of neighbors within the cutoff radius for each type of neighbor, then multiply the maximum by the “factor”. Finally the number is wrapped up to 4 divisible. The option “auto” is equivalent to “auto:1.1”.

**rcut:**

type: float, optional, default: 6.0

argument path: model/descriptor[se\_a\_tpe]/rcut

The cut-off radius.

**rcut\_smth:**

type: float, optional, default: 0.5

argument path: model/descriptor[se\_a\_tpe]/rcut\_smth

Where to start smoothing. For example the  $1/r$  term is smoothed from *rcut* to *rcut\_smth*

**neuron:**

type: list, optional, default: [10, 20, 40]

argument path: model/descriptor[se\_a\_tpe]/neuron

Number of neurons in each hidden layers of the embedding net. When two layers are of the same size or one layer is twice as large as the previous layer, a skip connection is built.

**axis\_neuron:**

type: int, optional, default: 4

argument path: model/descriptor[se\_a\_tpe]/axis\_neuron

Size of the submatrix of G (embedding matrix).

**activation\_function:**

type: str, optional, default: tanh

argument path: model/descriptor[se\_a\_tpe]/activation\_function

The activation function in the embedding net. Supported activation functions are “relu”, “relu6”, “softplus”, “sigmoid”, “tanh”, “gelu”.

**resnet\_dt:**

type: bool, optional, default: False

argument path: model/descriptor[se\_a\_tpe]/resnet\_dt

Whether to use a “Timestep” in the skip connection

**type\_one\_side:**

type: bool, optional, default: False

argument path: model/descriptor[se\_a\_tpe]/type\_one\_side

Try to build  $N_{\text{types}}$  embedding nets. Otherwise, building  $N_{\text{types}}^2$  embedding nets

**precision:**

type: str, optional, default: float64

argument path: model/descriptor[se\_a\_tpe]/precision

The precision of the embedding net parameters, supported options are “default”, “float16”, “float32”, “float64”.

**trainable:**

type: bool, optional, default: True  
argument path: model/descriptor[se\_a\_tpe]/trainable

If the parameters in the embedding net is trainable

**seed:**

type: int | NoneType, optional  
argument path: model/descriptor[se\_a\_tpe]/seed

Random seed for parameter initialization

**exclude\_types:**

type: list, optional, default: []  
argument path: model/descriptor[se\_a\_tpe]/exclude\_types

The Excluded types

**set\_davg\_zero:**

type: bool, optional, default: False  
argument path: model/descriptor[se\_a\_tpe]/set\_davg\_zero

Set the normalization average to zero. This option should be set when *atom\_ener* in the energy fitting is used

**type\_nchanl:**

type: int, optional, default: 4  
argument path: model/descriptor[se\_a\_tpe]/type\_nchanl

number of channels for type embedding

**type\_nlayer:**

type: int, optional, default: 2  
argument path: model/descriptor[se\_a\_tpe]/type\_nlayer

number of hidden layers of type embedding net

**numb\_aparam:**

type: int, optional, default: 0  
argument path: model/descriptor[se\_a\_tpe]/numb\_aparam

dimension of atomic parameter. if set to a value > 0, the atomic parameters are embedded.

When *type* is set to hybrid:

**list:**

type: list  
argument path: model/descriptor[hybrid]/list

A list of descriptor definitions

**fitting\_net:**

type: dict  
argument path: model/fitting\_net

The fitting of physical properties.

Depending on the value of *type*, different sub args are accepted.

**type:**



type: str (flag key), default: ener

argument path: model/fitting\_net/type

possible choices: *ener*, *dipole*, *polar*

The type of the fitting. See explanation below.

- *ener*: Fit an energy model (potential energy surface).
- *dipole*: Fit an atomic dipole model. Global dipole labels or atomic dipole labels for all the selected atoms (see *sel\_type*) should be provided by *dipole.npy* in each data system. The file either has number of frames lines and 3 times of number of selected atoms columns, or has number of frames lines and 3 columns. See *loss* parameter.
- *polar*: Fit an atomic polarizability model. Global polarizability labels or atomic polarizability labels for all the selected atoms (see *sel\_type*) should be provided by *polarizability.npy* in each data system. The file either has number of frames lines and 9 times of number of selected atoms columns, or has number of frames lines and 9 columns. See *loss* parameter.

When *type* is set to *ener*:

#### **numb\_fparam:**

type: int, optional, default: 0

argument path: model/fitting\_net[ener]/numb\_fparam

The dimension of the frame parameter. If set to >0, file *fparam.npy* should be included to provided the input fparams.

#### **numb\_aparam:**

type: int, optional, default: 0

argument path: model/fitting\_net[ener]/numb\_aparam

The dimension of the atomic parameter. If set to >0, file *aparam.npy* should be included to provided the input aparams.

#### **neuron:**

type: list, optional, default: [120, 120, 120]

argument path: model/fitting\_net[ener]/neuron

The number of neurons in each hidden layers of the fitting net. When two hidden layers are of the same size, a skip connection is built.

#### **activation\_function:**

type: str, optional, default: tanh

argument path: model/fitting\_net[ener]/activation\_function

The activation function in the fitting net. Supported activation functions are “relu”, “relu6”, “softplus”, “sigmoid”, “tanh”, “gelu”.

#### **precision:**

type: str, optional, default: float64

argument path: model/fitting\_net[ener]/precision

The precision of the fitting net parameters, supported options are “default”, “float16”, “float32”, “float64”.

#### **resnet\_dt:**

type: bool, optional, default: True

argument path: model/fitting\_net[ener]/resnet\_dt

Whether to use a “Timestep” in the skip connection

**trainable:**

type: `list | bool`, optional, default: `True`

argument path: `model/fitting_net[ener]/trainable`

Whether the parameters in the fitting net are trainable. This option can be

- `bool`: `True` if all parameters of the fitting net are trainable, `False` otherwise.
- `list of bool`: Specifies if each layer is trainable. Since the fitting net is composed by hidden layers followed by a output layer, the length of this list should be equal to `len(neuron)+1`.

**rcond:**

type: `float`, optional, default: `0.001`

argument path: `model/fitting_net[ener]/rcond`

The condition number used to determine the initial energy shift for each type of atoms.

**seed:**

type: `int | NoneType`, optional

argument path: `model/fitting_net[ener]/seed`

Random seed for parameter initialization of the fitting net

**atom\_ener:**

type: `list`, optional, default: `[]`

argument path: `model/fitting_net[ener]/atom_ener`

Specify the atomic energy in vacuum for each type

When `type` is set to `dipole`:

**neuron:**

type: `list`, optional, default: `[120, 120, 120]`

argument path: `model/fitting_net[dipole]/neuron`

The number of neurons in each hidden layers of the fitting net. When two hidden layers are of the same size, a skip connection is built.

**activation\_function:**

type: `str`, optional, default: `tanh`

argument path: `model/fitting_net[dipole]/activation_function`

The activation function in the fitting net. Supported activation functions are “`relu`”, “`relu6`”, “`softplus`”, “`sigmoid`”, “`tanh`”, “`gelu`”.

**resnet\_dt:**

type: `bool`, optional, default: `True`

argument path: `model/fitting_net[dipole]/resnet_dt`

Whether to use a “Timestep” in the skip connection

**precision:**

type: `str`, optional, default: `float64`

argument path: `model/fitting_net[dipole]/precision`

The precision of the fitting net parameters, supported options are “default”, “float16”, “float32”, “float64”.

**sel\_type:**

type: list | int | NoneType, optional

argument path: model/fitting\_net[dipole]/sel\_type

The atom types for which the atomic dipole will be provided. If not set, all types will be selected.

**seed:**

type: int | NoneType, optional

argument path: model/fitting\_net[dipole]/seed

Random seed for parameter initialization of the fitting net

When `type` is set to polar:

**neuron:**

type: list, optional, default: [120, 120, 120]

argument path: model/fitting\_net[polar]/neuron

The number of neurons in each hidden layers of the fitting net. When two hidden layers are of the same size, a skip connection is built.

**activation\_function:**

type: str, optional, default: tanh

argument path: model/fitting\_net[polar]/activation\_function

The activation function in the fitting net. Supported activation functions are “relu”, “relu6”, “softplus”, “sigmoid”, “tanh”, “gelu”.

**resnet\_dt:**

type: bool, optional, default: True

argument path: model/fitting\_net[polar]/resnet\_dt

Whether to use a “Timestep” in the skip connection

**precision:**

type: str, optional, default: float64

argument path: model/fitting\_net[polar]/precision

The precision of the fitting net parameters, supported options are “default”, “float16”, “float32”, “float64”.

**fit\_diag:**

type: bool, optional, default: True

argument path: model/fitting\_net[polar]/fit\_diag

Fit the diagonal part of the rotational invariant polarizability matrix, which will be converted to normal polarizability matrix by contracting with the rotation matrix.

**scale:**

type: list | float, optional, default: 1.0

argument path: model/fitting\_net[polar]/scale

The output of the fitting net (polarizability matrix) will be scaled by scale

**shift\_diag:**

type: bool, optional, default: True

argument path: model/fitting\_net[polar]/shift\_diag

Whether to shift the diagonal of polar, which is beneficial to training. Default is true.

**sel\_type:**

type: list | int | NoneType, optional

argument path: model/fitting\_net[polar]/sel\_type

The atom types for which the atomic polarizability will be provided. If not set, all types will be selected.

**seed:**

type: int | NoneType, optional

argument path: model/fitting\_net[polar]/seed

Random seed for parameter initialization of the fitting net

**modifier:**

type: dict, optional

argument path: model/modifier

The modifier of model output.

Depending on the value of *type*, different sub args are accepted.

**type:**

type: str (flag key)

argument path: model/modifier/type

possible choices: *dipole\_charge*

The type of modifier. See explanation below.

*-dipole\_charge*: Use WFCC to model the electronic structure of the system. Correct the long-range interaction

When *type* is set to *dipole\_charge*:

**model\_name:**

type: str

argument path: model/modifier[dipole\_charge]/model\_name

The name of the frozen dipole model file.

**model\_charge\_map:**

type: list

argument path: model/modifier[dipole\_charge]/model\_charge\_map

The charge of the WFCC. The list length should be the same as the *sel\_type*.

**sys\_charge\_map:**

type: list

argument path: model/modifier[dipole\_charge]/sys\_charge\_map

The charge of real atoms. The list length should be the same as the *type\_map*

**ewald\_beta:**

type: float, optional, default: 0.4

argument path: model/modifier[dipole\_charge]/ewald\_beta

The splitting parameter of Ewald sum. Unit is  $\text{\AA}^{-1}$

**ewald\_h:**

type: float, optional, default: 1.0

argument path: model/modifier[dipole\_charge]/ewald\_h

The grid spacing of the FFT grid. Unit is  $\text{\AA}$

**compress:**

type: dict, optional

argument path: model/compress

Model compression configurations

Depending on the value of *type*, different sub args are accepted.

**type:**

type: str (flag key), default: se\_e2\_a

argument path: model/compress/type

possible choices: se\_e2\_a

The type of model compression, which should be consistent with the descriptor type.

When *type* is set to se\_e2\_a (or its alias se\_a):

**compress:**

type: bool

argument path: model/compress[se\_e2\_a]/compress

The name of the frozen model file.

**model\_file:**

type: str

argument path: model/compress[se\_e2\_a]/model\_file

The input model file, which will be compressed by the DeePMD-kit.

**table\_config:**

type: list

argument path: model/compress[se\_e2\_a]/table\_config

The arguments of model compression, including extrapolate(scale of model extrapolation), stride(uniform stride of tabulation's first and second table), and frequency(frequency of tabulation overflow check).

**loss:**

type: dict, optional

argument path: loss

The definition of loss function. The loss type should be set to *tensor*, *ener* or left unset. .

Depending on the value of *type*, different sub args are accepted.

**type:**

type: str (flag key), default: ener

argument path: loss/type

possible choices: ener, tensor

The type of the loss. When the fitting type is *ener*, the loss type should be set to *ener* or left unset. When the fitting type is *dipole* or *polar*, the loss type should be set to *tensor*.

When `type` is set to `ener`:

**start\_pref\_e:**

type: int | float, optional, default: 0.02  
argument path: `loss[ener]/start_pref_e`

The prefactor of energy loss at the start of the training. Should be larger than or equal to 0. If set to none-zero value, the energy label should be provided by file `energy.npy` in each data system. If both `start_pref_energy` and `limit_pref_energy` are set to 0, then the energy will be ignored.

**limit\_pref\_e:**

type: int | float, optional, default: 1.0  
argument path: `loss[ener]/limit_pref_e`

The prefactor of energy loss at the limit of the training, Should be larger than or equal to 0. i.e. the training step goes to infinity.

**start\_pref\_f:**

type: int | float, optional, default: 1000  
argument path: `loss[ener]/start_pref_f`

The prefactor of force loss at the start of the training. Should be larger than or equal to 0. If set to none-zero value, the force label should be provided by file `force.npy` in each data system. If both `start_pref_force` and `limit_pref_force` are set to 0, then the force will be ignored.

**limit\_pref\_f:**

type: int | float, optional, default: 1.0  
argument path: `loss[ener]/limit_pref_f`

The prefactor of force loss at the limit of the training, Should be larger than or equal to 0. i.e. the training step goes to infinity.

**start\_pref\_v:**

type: int | float, optional, default: 0.0  
argument path: `loss[ener]/start_pref_v`

The prefactor of virial loss at the start of the training. Should be larger than or equal to 0. If set to none-zero value, the virial label should be provided by file `virial.npy` in each data system. If both `start_pref_virial` and `limit_pref_virial` are set to 0, then the virial will be ignored.

**limit\_pref\_v:**

type: int | float, optional, default: 0.0  
argument path: `loss[ener]/limit_pref_v`

The prefactor of virial loss at the limit of the training, Should be larger than or equal to 0. i.e. the training step goes to infinity.

**start\_pref\_ae:**

type: int | float, optional, default: 0.0  
argument path: `loss[ener]/start_pref_ae`

The prefactor of `atom_ener` loss at the start of the training. Should be larger than or equal to 0. If set to none-zero value, the `atom_ener` label should be provided by file `atom_ener.npy` in each data system. If both `start_pref_atom_ener` and `limit_pref_atom_ener` are set to 0, then the `atom_ener` will be ignored.

**limit\_pref\_ae:**

type: int | float, optional, default: 0.0

argument path: `loss[ener]/limit_pref_ae`

The prefactor of atom\_ener loss at the limit of the training, Should be larger than or equal to 0. i.e. the training step goes to infinity.

**relative\_f:**

type: float | NoneType, optional

argument path: `loss[ener]/relative_f`

If provided, relative force error will be used in the loss. The difference of force will be normalized by the magnitude of the force in the label with a shift given by *relative\_f*, i.e.  $DF_i / (\|F\| + \text{relative\_f})$  with  $DF$  denoting the difference between prediction and label and  $\|F\|$  denoting the L2 norm of the label.

When *type* is set to `tensor`:

**pref:**

type: int | float

argument path: `loss[tensor]/pref`

The prefactor of the weight of global loss. It should be larger than or equal to 0. It controls the weight of loss corresponding to global label, i.e. `'polarizability.npy'` or `dipole.npy`, whose shape should be `#frames x [9 or 3]`. If it's larger than 0.0, this `numpy` should be included.

**pref\_atomic:**

type: int | float

argument path: `loss[tensor]/pref_atomic`

The prefactor of the weight of atomic loss. It should be larger than or equal to 0. It controls the weight of loss corresponding to atomic label, i.e. `atomic_polarizability.npy` or `atomic_dipole.npy`, whose shape should be `#frames x ([9 or 3] x #selected atoms)`. If it's larger than 0.0, this `numpy` should be included. Both *pref* and *pref\_atomic* should be provided, and either can be set to 0.0.

**learning\_rate:**

type: dict

argument path: `learning_rate`

The definition of learning rate

Depending on the value of *type*, different sub args are accepted.

**type:**

type: str (flag key), default: `exp`

argument path: `learning_rate/type`

possible choices: `exp`

The type of the learning rate.

When *type* is set to `exp`:

**start\_lr:**

type: float, optional, default: 0.001

argument path: `learning_rate[exp]/start_lr`

The learning rate at the start of the training.

**stop\_lr:**

type: float, optional, default: 1e-08  
argument path: `learning_rate[exp]/stop_lr`

The desired learning rate at the end of the training.

**decay\_steps:**

type: int, optional, default: 5000  
argument path: `learning_rate[exp]/decay_steps`

The learning rate is decaying every this number of training steps.

**training:**

type: dict  
argument path: `training`

The training options.

**training\_data:**

type: dict  
argument path: `training/training_data`

Configurations of training data.

**systems:**

type: list | str  
argument path: `training/training_data/systems`

The data systems for training. This key can be provided with a list that specifies the systems, or be provided with a string by which the prefix of all systems are given and the list of the systems is automatically generated.

**set\_prefix:**

type: str, optional, default: set  
argument path: `training/training_data/set_prefix`

The prefix of the sets in the *systems*.

**batch\_size:**

type: list | str | int, optional, default: auto  
argument path: `training/training_data/batch_size`

This key can be

- list: the length of which is the same as the *systems*. The batch size of each system is given by the elements of the list.
- int: all *systems* use the same batch size.
- string “auto”: automatically determines the batch size so that the batch\_size times the number of atoms in the system is no less than 32.
- string “auto:N”: automatically determines the batch size so that the batch\_size times the number of atoms in the system is no less than N.

**auto\_prob:**

type: str, optional, default: `prob_sys_size`, alias: *auto\_prob\_style*  
argument path: `training/training_data/auto_prob`

Determine the probability of systems automatically. The method is assigned by this key and can be



- “prob\_uniform” : the probability all the systems are equal, namely  $1.0/\text{self.get\_nsystems}()$
- “prob\_sys\_size” : the probability of a system is proportional to the number of batches in the system
- “prob\_sys\_size;stt\_idx:end\_idx:weight;stt\_idx:end\_idx:weight;...” : the list of systems is divided into blocks. A block is specified by *stt\_idx:end\_idx:weight*, where *stt\_idx* is the starting index of the system, *end\_idx* is then ending (not including) index of the system, the probabilities of the systems in this block sums up to *weight*, and the relatively probabilities within this block is proportional to the number of batches in the system.

**sys\_probs:**

type: list | NoneType, optional, default: None, alias: *sys\_weights*

argument path: training/training\_data/sys\_probs

A list of float if specified. Should be of the same length as *systems*, specifying the probability of each system.

**validation\_data:**

type: dict | NoneType, optional, default: None

argument path: training/validation\_data

Configurations of validation data. Similar to that of training data, except that a *numb\_btch* argument may be configured

**systems:**

type: list | str

argument path: training/validation\_data/systems

The data systems for validation. This key can be provided with a list that specifies the systems, or be provided with a string by which the prefix of all systems are given and the list of the systems is automatically generated.

**set\_prefix:**

type: str, optional, default: set

argument path: training/validation\_data/set\_prefix

The prefix of the sets in the *systems*.

**batch\_size:**

type: list | str | int, optional, default: auto

argument path: training/validation\_data/batch\_size

This key can be

- list: the length of which is the same as the *systems*. The batch size of each system is given by the elements of the list.
- int: all *systems* use the same batch size.
- string “auto”: automatically determines the batch size so that the batch\_size times the number of atoms in the system is no less than 32.
- string “auto:N”: automatically determines the batch size so that the batch\_size times the number of atoms in the system is no less than N.

**auto\_prob:**

type: str, optional, default: prob\_sys\_size, alias: *auto\_prob\_style*

argument path: training/validation\_data/auto\_prob

Determine the probability of systems automatically. The method is assigned by this key and can be

- “prob\_uniform” : the probability all the systems are equal, namely  $1.0/\text{self.get\_nsystems}()$
- “prob\_sys\_size” : the probability of a system is proportional to the number of batches in the system
- “prob\_sys\_size;stt\_idx:end\_idx:weight;stt\_idx:end\_idx:weight;...” : the list of systems is divided into blocks. A block is specified by *stt\_idx:end\_idx:weight*, where *stt\_idx* is the starting index of the system, *end\_idx* is then ending (not including) index of the system, the probabilities of the systems in this block sums up to *weight*, and the relatively probabilities within this block is proportional to the number of batches in the system.

**sys\_probs:**

type: list | NoneType, optional, default: None, alias: *sys\_weights*

argument path: training/validation\_data/sys\_probs

A list of float if specified. Should be of the same length as *systems*, specifying the probability of each system.

**numb\_btch:**

type: int, optional, default: 1, alias: *numb\_batch*

argument path: training/validation\_data/numb\_btch

An integer that specifies the number of systems to be sampled for each validation period.

**numb\_steps:**

type: int, alias: *stop\_batch*

argument path: training/numb\_steps

Number of training batch. Each training uses one batch of data.

**seed:**

type: int | NoneType, optional

argument path: training/seed

The random seed for getting frames from the training data set.

**disp\_file:**

type: str, optional, default: *lcueve.out*

argument path: training/disp\_file

The file for printing learning curve.

**disp\_freq:**

type: int, optional, default: 1000

argument path: training/disp\_freq

The frequency of printing learning curve.

**numb\_test:**

type: list | str | int, optional, default: 1

argument path: training/numb\_test

Number of frames used for the test during training.

**save\_freq:**

type: int, optional, default: 1000

argument path: training/save\_freq

The frequency of saving check point.

**save\_ckpt:**

type: str, optional, default: model.ckpt

argument path: training/save\_ckpt

The file name of saving check point.

**disp\_training:**

type: bool, optional, default: True

argument path: training/disp\_training

Displaying verbose information during training.

**time\_training:**

type: bool, optional, default: True

argument path: training/time\_training

Timing during training.

**profiling:**

type: bool, optional, default: False

argument path: training/profiling

Profiling during training.

**profiling\_file:**

type: str, optional, default: timeline.json

argument path: training/profiling\_file

Output file for profiling.

**tensorboard:**

type: bool, optional, default: False

argument path: training/tensorboard

Enable tensorboard

**tensorboard\_log\_dir:**

type: str, optional, default: log

argument path: training/tensorboard\_log\_dir

The log directory of tensorboard outputs



## DEVELOPER GUIDE

- Python API
- C++ API
- Coding Conventions
- Atom Type Embedding



## LICENSE

The project DeePMD-kit is licensed under [GNU LGPLv3.0](#).





## AUTHORS AND CREDITS

### 9.1 Package Contributors

- amacadmus
- AnguseZhang
- denghuilu
- bwang-ecnu
- frankhan91
- GeiduanLiu
- gzq942560379
- haidi-ustc
- hlyang1992
- hsulab
- iProzd
- JiabinYang
- marian-code
- njzjz
- tuoping
- wsyxbcl
- ylxiaoc
- YWolfeee
- zhouwei25
- ZiyaoLi

## 9.2 Other Credits

- Zhang ZiXuan for designing the Deepmodeling logo.
- Everyone on the *Deepmodeling mailing list* for contributing to many discussions and decisions!

(If you have contributed to the `deepmd-kit` core package and your name is missing, please send an email to the contributors, or open a pull request in the [deepmd-kit repository](#))

- `genindex`
- `modindex`
- `search`